LOCAL CONVEXITY AND STARSHAPED SETS

BY

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ABSTRACT

Previously [7] we proved among other results that a closed connected set in E_n which has a unique point of local nonconvexity is starshaped. Here we characterize a fairly large class of plane sets whose points of local nonconvexity are so arranged that starshapedness follows. This theory determines as a special case the simple closed polygonal regions which are starshaped. In order to proceed simply we utilize the following notations and definitions.

NOTATIONS. The interior, closure and boundary of a set S in Euclidean *n*-space E_n are denoted by int S, cl S and bd S respectively. The closed segment joining points $x \in E_n$, $y \in E_n$ is denoted by xy. Set union, intersection and difference are indicated by \cup, \cap and \sim respectively. The symbol conv S denotes the convex hull of the set S. The symbol 0 denotes the empty set.

DEFINITION 1. A point $x \in S$ is a point of local convexity of S if there exists a neighborhood N of x such that $N \cap S$ is convex; otherwise x is called a point of local nonconvexity. The set of all points of local nonconvexity of S is denoted by Q.

DEFINITION 2. A set S is starshaped with respect to a point p if $px \subset S$ for all points $x \in S$.

DEFINITION 3. The two closed rays of a line L which have only a point $x \in L$ in common are called complementary rays. If R(x) is a ray with endpoint x, its complementary ray is denoted by R'(x).

DEFINITION 4. A ray R(x) with endpoint $x \in bd S$ is an external ray of support to the int S if $R(x) \cap int S = 0$.

DEFINITION 5. If x is a boundary point of a set S, then K(x) is the union of all the external rays of support to int S at x. A boundary point $x \in S$ is called a onesided point of external support of int S if

 $K(x) \neq 0$,

and if K(x) lies in a closed half-space which contains x in its boundary. The set K(x) is called an external cone of support. The union of all the complementary rays R'(x) where $R(x) \subset K(x)$ is denoted by

K'(x).

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The following theorem is one of Krasnoselskii type [2], and it is also related to results developed by Eugene Robkin in his thesis [5]. For another kind of theorem of Krasnoselskii type for polygonal regions see Molnar [4].

THEOREM 1. Suppose $S \subset E_2$ is a bounded plane set which is the closure of an open connected set.

Then S is starshaped if and only if both of the following conditions hold.

(a) Each point of local nonconvexity $x \in S$ has a nonempty cone of external support K(x) to int S at x.

(b) If x_1, x_2, x_3 are three points of local nonconvexity of S (they need not be distinct) which are also one-sided points of external support to int S, then there exist three external rays of support $R(x_1), R(x_2), R(x_3)$ to int S at x_1, x_2, x_3 respectively whose corresponding complementary rays $R'(x_1), R'(x_2), R'(x_3)$ are concurrent and meet in S, so that

(1)
$$S \cap R'(x_1) \cap R'(x_2) \cap R'(x_3) \neq 0.$$

Proof. We will prove that conditions (a) and (b) imply that S is starshaped. Let Q_1 denote the set of all points of local nonconvexity of S which are also onesided points of external support to int S (see Definitions 1 and 5). First, observe that if S is convex then $Q_1 = 0$; however, in this case S is also starshaped, being convex. Hence, suppose S is not convex. Since int $S \neq 0$, when int S is not convex a theorem of Leja and Wilkosz [3] implies that a point q of local nonconvexity of S exists which is the midpoint of the bounding diameter of a closed semicircular region which, except for q, lies in int S. Clearly such a point q is in Q_1 , so that $Q_1 \neq 0$.

Now define C(x) as follows,

$$C(x) \equiv (\operatorname{conv} K'(x)) \cap \operatorname{conv} S$$

where $x \in Q_1$ (see Definition 5). Since conv K'(x) is closed, and since S is compact, the set C(x) is compact. By hypothesis, every three of fewer members of the collection of compact convex sets

$$\{C(x), x \in Q_1\}$$

have at least one point in common. Helly's Theorem [1] then implies that

(2)
$$M \equiv \bigcap_{x \in Q_1} C(x) \neq 0.$$

Let $p \in M$. We will prove that S is starshaped relative to p. Firstly, if $p \notin S$, then since S is compact and connected there exists a cross-cut of the complement of S, say uv, such that

(3)
$$u \in S, v \in S, S \cap (uv \sim u \sim v) = 0, (p, u, v)$$
 are collinear.

Secondly, if $p \in S$ and if there exists a point $y \in S$ such that

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there again exists a cross-cut of the complement of S, uv, such that (3) holds. Hence, to prove $py \,\subset S$ for each $y \in S$, we prove that (3) cannot hold. Suppose (3) does hold. Since S is closed and connected, the segment uv divides a component of the complement of S, say K, such that $K \sim uv$ contains at least one bounded component. Let K_1 be such a bounded component of $K \sim uv$. This component K_1 of $K \sim uv$ abuts uv from one side of uv. Let H be that closed half-plane whose boundary contains uv and in which K_1 abuts uv. Consider the set

$$K^* \equiv \operatorname{cl}\,\operatorname{conv}(H \cap K_1).$$

Since K^* is a compact convex set with int $K^* \neq 0$, and since int $K^* \subset H$, there must exist a point

$$x \in bd K^*$$

and a line of support L to K^* such that

$$L \cap K^* = x, \ x \in S$$

and such that p and uv lie in the same open half-space bounded by L. Since $u \in S$, $v \in S$, $u \neq v$, since S = cl int S, and since int S is open and connected, for each $\varepsilon > 0$ there exists points $u_1 \in int S$, $v_1 \in int S$ such that

 $\left\| u_1 - u \right\| < \varepsilon, \left\| v_1 - v \right\| < \varepsilon$

and such that a polygonal path $P(u_1, v_1)$ exists in int S joining u_1 and v_1 . Now, clearly x is a point of local nonconvexity of S otherwise the convexity of $S \cap N$ for some neighborhood N of x would violate condition (5). Furthermore, one can choose a bounded component K_1 of $K \sim uv$ and an $\varepsilon > 0$ (above) so that K(x)must be in the closed half space bounded by L which contains p and uv, because

$$K(x) \cap P(u_1, v_1) = 0.$$

However, in this case, no ray R(x) in conv K(x) exists whose complementary ray R'(x) contains p. This, however contradicts (2), since $p \in M$. Hence, we have arrived at a contradiction. Therefore, S is starshaped.

Since the converse situation is trivial, we have proved Theorem 1.

Theorem 1 has an interesting form when the boundary of S is a simple closed polygon in E_2 . To state it we first note the following.

DEFINITION 6. A vertex x of a simple closed polygon P is called reentrant if x is a point of local nonconvexity of the closed bounded polygonal set whose boundary is P.

THEOREM 2. Let S be a bounded closed set in E_2 whose boundary is a simple closed polygon. Suppose that for each three reentrant vertices of bdS, x_1, x_2, x_3

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there exist three external rays of support at x_1, x_2, x_3 respectively to int S whose corresponding complementary rays are concurrent (see (1)) and meet in S. Then S is starshared

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Proof. Theorem 2 follows from Theorem 1 since conditions (a) and (b) are automatically both satisfied.

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